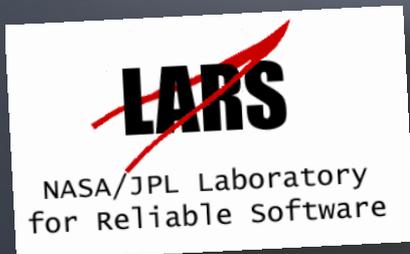
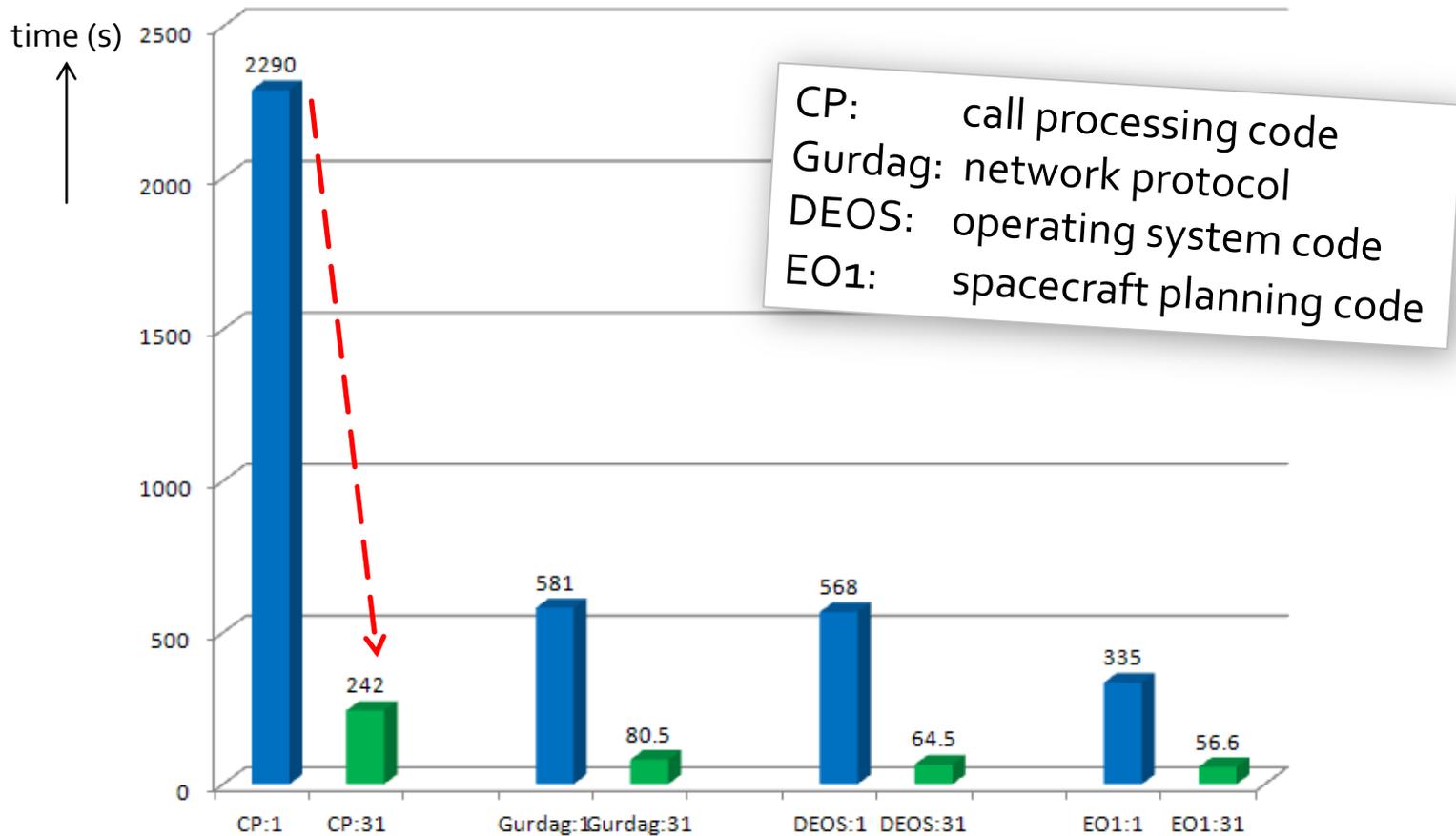


# Speeding up the Analysis of Complex Software with Parallel Model Checking



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# what would it take to achieve speedups like these?



# parallel breadth-first search

## PROS

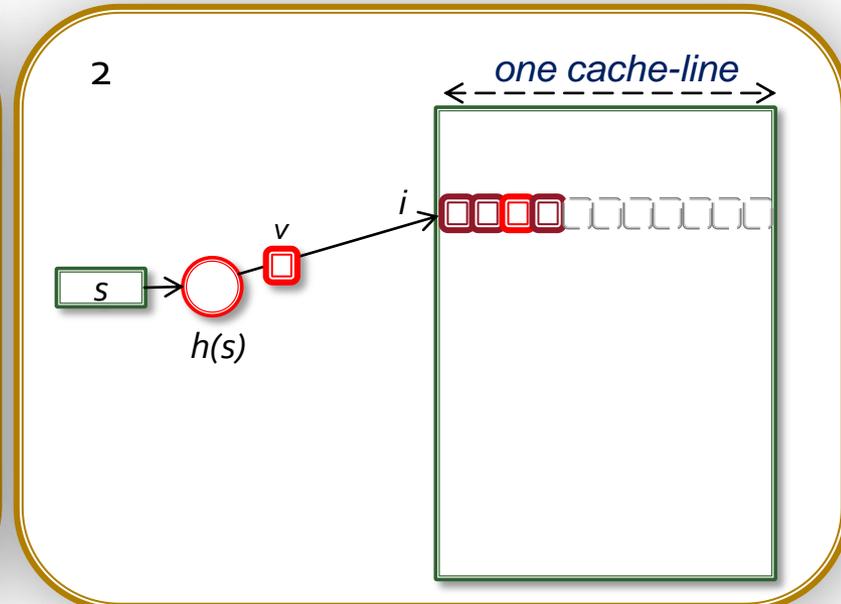
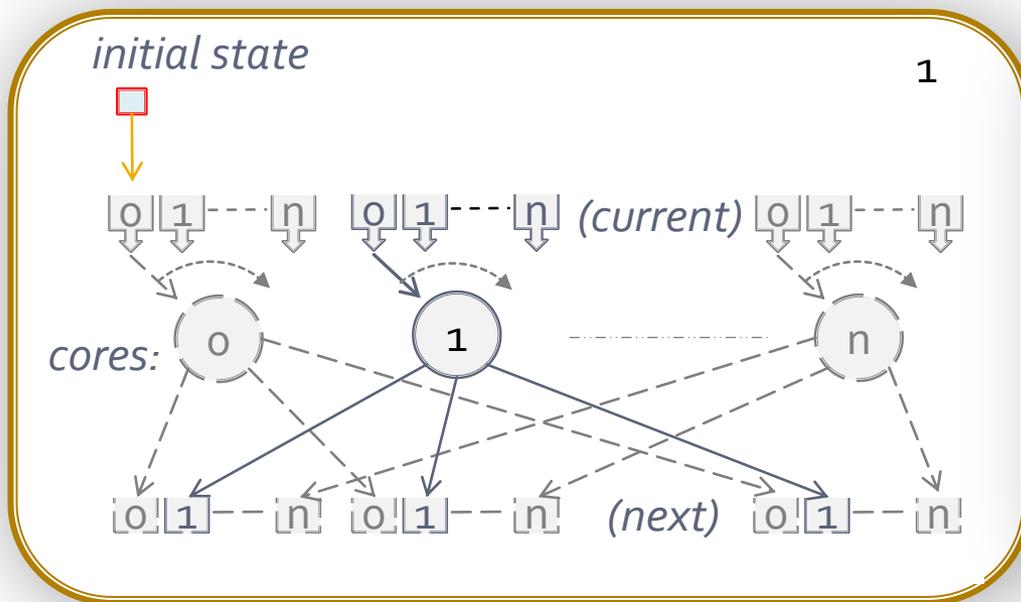
- simplest search mode for a logic model checker
  - basic reachability analysis
- there is no ordering requirement on state exploration
  - relatively easy to parallelize
- always finds the *shortest* counter-example first

## CONS

1. parallelization requires locks and synchronization
  - which can limit performance
2. often requires more memory than a depth-first search
3. traditionally restricted to the subclass of LTL defining *safety* properties
  - invariants, absence of assertion violations, absence of deadlock, etc.

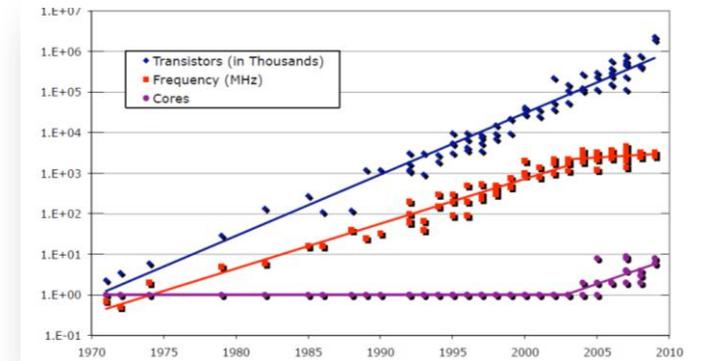
# 1: eliminate locks

- design a lock-free algorithm
  1. lock-free & contention-free queues
  2. a modified cache-aware hash-table



# 2: requires (modestly) more memory

- both the *number of cores* and the *size of RAM* grows with Moore's curve: i.e., exponentially fast
  - but clock-speeds remain constant
- this means:
  - memory is *not* the bottleneck
  - performance is linked to clockspeeds *unless* we exploit parallelism



source: Olukotun, Hammond, Sutter, Smith, Batten & Asanovic

# 3: traditionally restricted to safety

*safety*:  $p$  is invariant

*liveness*:  $\Box (p \rightarrow \langle \rangle q)$  – when  $p$  occurs, eventually  $q$  will occur as well

**safety** properties can be checked with a breadth-first search

**liveness** properties are harder:

they require a *cycle detection* algorithm

this can be done efficiently with a *depth*-first search

at up to *twice* the cost of a standard depth-first search

the best known methods for verifying **liveness** with a breadth-first search carry excessive overhead:

the cost becomes *quadratic*, for instance ( $R$ =size of graph)

if  $R = 5 \cdot 10^6$  then  $2 \cdot R = 10 \cdot 10^6$ , but  $R^2 = 25 \cdot 10^{12}$

if  $R$  takes *2 seconds*,  $2 \cdot R$  takes 4 sec, and  $R^2$  takes  *$10^7$  seconds (11 days)*

# 3: bounded search

## a "piggyback" algorithm

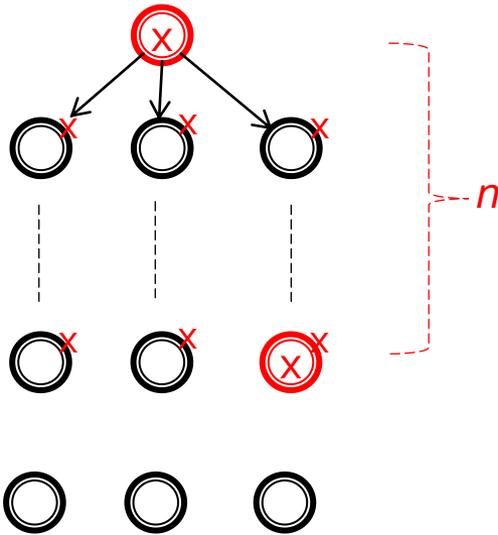
$\Box (p \rightarrow \langle \rangle_n q)$

bounded liveness

when  $p$  happens,  $q$  will happen as well *within  $n$  steps*

$\langle \rangle (p \wedge \Box_n !q)$

signature of counter-examples



"piggyback search"

*bounded search*

we perform a check on paths of max length  $n$

PRO:

simple to implement

adds a small *constant* memory overhead for propagating *tags*, but adds *virtually no time*

the cost is:  $c.R$  with  $1 < c \ll 2$

CON:

to limit memory overhead, we carry only 1 *tag field*

this means we can miss counter-examples: we accept a small chance of incompleteness

remarkably: *the algorithm works almost always*



# synopsis

- the new parallel breadth-first search option, with the piggyback algorithm, delivers a remarkable increase in performance on multi-core systems
  - allowing us to tackle more complex software verification problems (medical, automotive, aerospace)
  - the extension described here will become part of Spin version 6.2.0
  - a paper "*Parallelizing the Spin Model Checker*" was submitted for publication

